



## **DYNAMIC PROGRAMMING**

divide an optimisation problem into incremental subproblems for which optimal solutions can be obtained

enables identifying the optimal among multiple possible solutions

characterised by working 'backward' (*i.e.*, reverse recursion)

<b>REVERSE RECURSION 1</b>							
	$Q_{f,j} = (1 - p_j) (Q_i - c_j + f_j v_j)$						
		j = 1 (safe)	j = 2 (risky)				
	р	0	0.5				
	С	1	1				
	f	0	0.5				
	v	0	4				

<b>REVERSE RECURSION 2</b>							
P(s	survival, j) =	(1 - p <sub>j</sub> ) (1 - p <sub>j</sub> ) f <sub>j</sub> 0	$\begin{array}{l} \mathbf{Q}_{i} - \mathbf{c}_{j} > 0 \\ \mathbf{Q}_{i} - \mathbf{c}_{j} \leq 0 \\ \mathbf{Q}_{f} \leq 0 \end{array}$				
p c f v	j = 1 (safe) 0 1 0 0	j = 2 (risky) 0.5 1 0.5 4					



<b>REVERSE RECURSION 3</b>								
	$Q_{f,j} = (1 - p_j) (Q_i - C_j + f_j V_j)$							
	j = 1 (s	j = 1 (safe)		isky)				
$\mathbf{Q}_{i}$	$\mathbf{Q}_{\mathrm{f}}$	Ρ	$\mathbf{Q}_{\mathrm{f}}$	Р				
2	1	1	1.5	0.5				
1	0	0	1	0.25				

